

Sensory-Motor Integration Lab

Master/PhD positions

➤ Novel, biologically inspired biped locomotion control

• Applications:

- Biped / humanoid robots
- Locomotion rehabilitation

• Requirements:

- Strong background and interest in Dynamical systems

• Contact:

- Assoc. Prof. Miriam Zacksenhouse
mermz@tx.technion.ac.il
- Jonathan Spitz
spitz.jonathan@gmail.com

