Smirn - סמיナー

הנך מוזמן/ת להרצאה סמינריונית של הפקולטה להנדסת מכניקה, שתחולק ביום ב' 18.01.2021 (ה' ובשבט תשפ”א), בשעה 14:30 ב’amペンגט החודש: 97718722005

https://technion.zoom.us/j/97718722005

מרצה:

Professor Yakov Ben-Haim
Faculty of Mechanical Engineering
Technion — Israel Institute of Technology
yakov@technion.ac.il
http://info-gap.com http://yakov.technion.ac.il
Tel: +972-4-829-3262, +972-50-750-1402 Fax: +972-4-829-5711

על הנושא:

Ethics and Uncertainty: An Info-Gap Approach

The seminar will be given in English

Consider these questions:

- You are designing a device that can result in vast destruction in an aggressive adversarial country, but you are unsure whether that destruction will be military or civilian. However, without this device, the adversary can inflict vast destruction on your country. Should you proceed?
- You are developing a technology whose long-range environmental impact is unknown, but may be either severely detrimental or tremendously beneficial. Only time will tell. Should you proceed?

Kant’s deontological ethics posits universal moral commands that must be strictly observed. In choosing between alternative actions one must choose that which most closely adheres to these moral commands. In other words, Kant’s deontology requires one to optimize the fidelity to specified moral requirements. However, info-gap theory demonstrates that this optimization will have negligible robustness against uncertainty. In other words, Kantian deontology is not reliable for insuring ethical behavior when facing deep uncertainty. We demonstrate an alternative approach, based on satisficing the degree of fidelity to the moral commands, and maximizing the robustness to uncertainty. We show that decisions based on this robust-satisficing approach may or may not agree with decisions based on Kantian deontology.

Selected publications:


Additional information: http://info-gap.com

ברכה,

Yakov Ben-Haim