



הטכניון – מכון טכנולוגי לישראל  
הפקולטה להנדסת מכונות



## The Technion Autonomous Systems Program

TECHNION – Israel Institute of Technology  
Faculty of Mechanical Engineering

### סמינר - SEMINAR

הנך מוזמן/ת לסמינר משותף לפקולטה להנדסת מכונות ולתוכנית הטכניון במערכות אוטונומיות,  
שיתקיים ביום ה' 30.07.15 (יד' באב, תשע"ה), בבניין דן-קאהן, אודיטוריום 1 בשעה 14:30

תרצה:

**Hadas Kress-Gazit, PhD.**

Associate Professor

Sibley School of Mechanical and Aerospace Engineering

Cornell University, 210 Upson Hall

<http://verifiablerobotics.com/>

על הנושא:

# High-level verifiable robotics

להלן תקציר ההרצאה:

The recent DARPA Robotics Challenge has demonstrated that while robots have advanced significantly in the past few decades in terms of both hardware and software, even the best of them take almost an hour to perform tasks a person can do in 5 minutes. This is mostly due to the human-in-the-loop; Instead of providing high-level instructions such as “turn the valve”, most teams had expert operators looking through the robot’s “eyes” and controlling most of the robot’s actions. Furthermore, some of the falls during the challenge are attributed to operator error. For such challenges, and for robots to be integrated into society in general, autonomy, and more specifically, verifiable autonomy, is a key factor for success.

To achieve autonomy and true human robot collaboration, two key challenges must be addressed; people should be able to easily interact with robots, and robots must always do as they are told. In this talk I will discuss the work done in my group to address these challenges; the use of language, abstractions and temporal logic to capture high-level task specifications, and the development of formal methods that automatically either transform task specifications into correct robot behavior, if such behavior exists, or provide explanations to the user of why a robot might fail.

Bio:

Hadas Kress-Gazit is an Associate Professor at the Sibley School of Mechanical and Aerospace Engineering at Cornell University. She received her Ph.D. in Electrical and Systems Engineering from the University of Pennsylvania in 2008 and has been at Cornell since 2009. Her research focuses on formal methods for robotics and automation and more specifically on creating verifiable robot controllers for complex high-level tasks using logic, verification, synthesis, hybrid systems theory and computational linguistics. She received an NSF CAREER award in 2010 and a DARPA Young Faculty Award in 2012.

בברכה,

תאריך: 30/7/15

מרכז הסמינרים

מארח: פרופ' ח אלון וולף